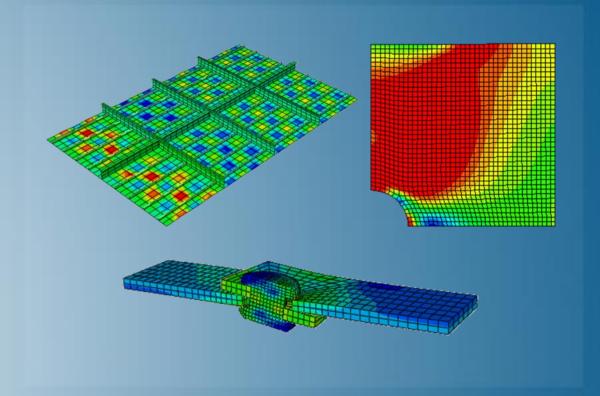


Modeling Contact and Resolving Convergence Issues with Abaqus Abaqus 2020





3DEXPERIENCE[®]

About this Course

Course objectives

Upon completion of this course you will be able to:

- Define general contact and contact pairs
- Define appropriate surfaces (rigid or deformable)
- Model frictional contact
- Model large sliding between deformable bodies
- Resolve overclosures in interference fit problems
- Understand how nonlinear problems are solved in Abaqus
- Develop Abaqus models that will converge
- Identify modeling errors that cause models to experience convergence difficulties
- Recognize when a problem is too difficult or too ill-posed to be solved effectively

Targeted audience

Simulation Analysts

Prerequisites

This course is recommended for engineers with experience using Abaqus



Day 1

- Lesson 1 Introduction to Nonlinear FEA
- Lesson 2 Contact Workflow
 - Workshop 1 Compression of a Rubber Seal
- Lesson 3 Nonlinear FEA with Abaqus/Standard
 - Workshop 2 Bolted Flange Analysis
- Lesson 4 Why Abaqus Fails to Converge
 - Workshop 3 Crimp Forming Analysis (Part 1)

Day 2

- Lesson 5 Surface based contact
- Lesson 6 Solution of Unstable Problems
 - Workshop 3 Crimp Forming Analysis (Part 2)
 - Workshop 4 Reinforced Plate Under Compressive Loads
- Lesson 7 Contact Properties
 - Workshop 5 Disk Forging Analysis
- Lesson 8 Convergence Problems: Element Behavior
 - Workshop 6 Element selection

Day 3

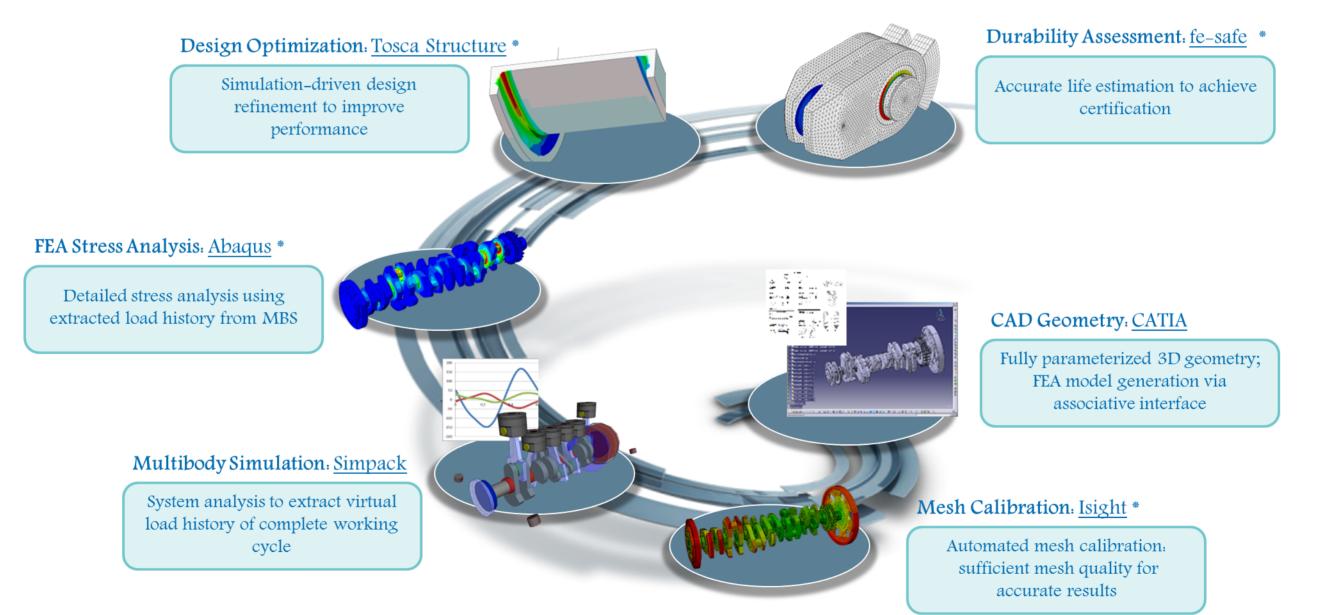
- Lesson 9 Convergence Problems: Materials
 - Workshop 7 Limit Load Analysis
 - Workshop 8 Ball Impact (optional)
- Lesson 10 Interference Fits
 - Workshop 9 Interference Fit Analysis
- Lesson 11 Convergence Problems: Constraints and Loading
- Lesson 12 Modeling Tips
 - Workshop 10 Snap Fit Analysis
 - Workshop 11 Analysis of a Radial Shaft Seal (optional)

Additional Material - Appendices

- Appendix 1 Node-to-Surface Formulation
- Appendix 2 Contact Elements
- Appendix 3 Dynamic Contact using Implicit Integration
- Appendix 4 Contact Logic and Diagnostics Tools
- Appendix 5 Additional Contact Features
- Appendix 6 Additional Contact Output
- Appendix 7 Advanced Friction Models
- Appendix 8 Contact Clearance
- Appendix 9 Geometric Smoothing
- Appendix 10 Resolving Overconstraints

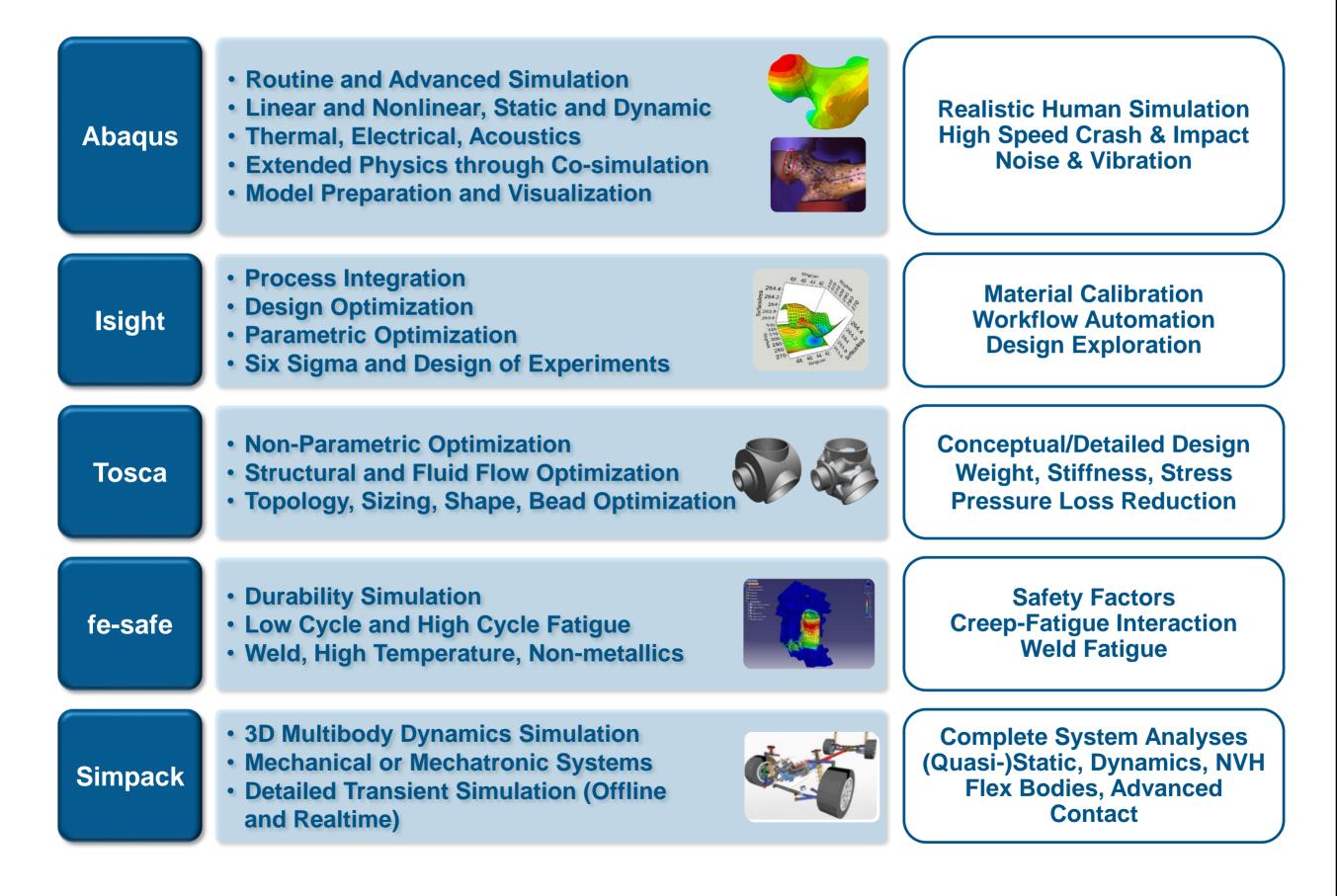
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Revision Status

Lesson 1	11/19	Updated for Abaqus 2020
Lesson 2	11/19	Updated for Abaqus 2020
Lesson 3	11/19	Updated for Abaqus 2020
Lesson 4	11/19	Updated for Abaqus 2020
Lesson 5	11/19	Updated for Abaqus 2020
Lesson 6	11/19	Updated for Abaqus 2020
Lesson 7	11/19	Updated for Abaqus 2020
Lesson 8	11/19	Updated for Abaqus 2020
Lesson 9	11/19	Updated for Abaqus 2020
Lesson 10	11/19	Updated for Abaqus 2020
Lesson 11	11/19	Updated for Abaqus 2020
Lesson 12	11/19	Updated for Abaqus 2020
Appendix 1	11/19	Updated for Abaqus 2020
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Workshop 10	11/19	Updated for Abaqus 2020
Workshop 11	11/19	Updated for Abaqus 2020

Lesson 1: Introduction to Nonlinear FEA

Lesson content:

- What is Convergence?
- When is a Problem Nonlinear?
- Properties of Linear Problems in Mechanics
- Properties of Nonlinear Problems in Mechanics
- Numerical Techniques for Solving Nonlinear Problems



Lesson 2: Contact Workflow

Lesson content:

- Defining General Contact
- Defining Contact Pairs
- Defining Surfaces
- Workshop Preliminaries
- Workshop 1: Compression of a Rubber Seal (IA)
- Workshop 1: Compression of a Rubber Seal (KW)





Lesson 3: Nonlinear FEA with Abaqus/Standard

Lesson content:

- Nonlinear Solution Methods
- Abaqus/Standard Convergence Criteria: An Overview
- Automatic Time Incrementation
- Contact Convergence
- Workshop 2: Bolted Flange Analysis (IA)
- Workshop 2: Bolted Flange Analysis (KW)





Lesson 4: Why Abaqus Fails to Converge

Lesson content:

- The Basic Problems
- Understanding the Warning Messages
- Helping Abaqus Find a Converged Solution
- Workshop 3 (Part 1): Crimp Forming Analysis (IA)
- Workshop 3 (Part 1): Crimp Forming Analysis (KW)





Lesson 5: Surface-based Contact

Lesson content:

- Contact Formulations
- Contact Discretization
- Contact Enforcement Methods
- Relative Sliding Between Bodies
- Contact Output
- Summary

Lesson 6: Solution of Unstable Problems

Lesson content:

- Unstable Quasi-Static Problems
- Globally Unstable Problems
- Stabilization of Local Instabilities
- Symptoms of Local Instability
- Automated Viscous Damping
- Implicit Dynamics
- Examples
- Stabilization of Initial Rigid Body Motion
- Workshop 3 (Part 2): Crimp Forming Analysis (IA)
- Workshop 3 (Part 2): Crimp Forming Analysis (KW)
- Workshop 4: Reinforced Plate Under Compressive Loads (IA)
- Workshop 4: Reinforced Plate Under Compressive Loads (KW)





Lesson 7: Contact Properties

Lesson content:

- Pressure-Overclosure Models
- Friction Models
- Friction Enforcement
- Workshop 5: Disk Forging Analysis (IA)
- Workshop 5: Disk Forging Analysis (KW)





Lesson 8: Convergence Problems: Element Behavior

Lesson content:

- Hourglassing in Reduced-Integration Elements
- Checkerboarding
- Ill-Conditioning
- Workshop 6: Element Selection (IA)
- Workshop 6: Element Selection (KW)





Lesson 9: Convergence Problems: Materials

Lesson content:

- Large Strains and Linear Elasticity
- Unstable Material Behavior
- Example: Plate with a Hole
- Unsymmetric Material Stiffness
- Example: Concrete Slump Test
- Workshop 7: Limit Load Analysis (IA)
- Workshop 7: Limit Load Analysis (KW)
- Workshop 8: Ball Impact (IA)
- Workshop 8: Ball Impact (KW)





Lesson 10: Interference Fits

Lesson content:

- Initial Overclosure
- Strain-free Adjustments
- Interference Fit Problems
- Interference Fit Techniques for General Contact
- Interference Fit Techniques for Contact Pairs
- Interference Fit Example
- Geometric Smoothing for Curved Surfaces
- Workshop 9: Interference Fit Analysis (IA)
- Workshop 9: Interference Fit Analysis (KW)





Lesson 11: Convergence Problems: Constraints & Loading

Lesson content:

- General Remarks
- Overconstraints Detected during Model Processing
- Overconstraints Detected during Analysis Execution
- Controlling the Overconstraint Checks
- Nonconservative Loads



Lesson 12: Modeling Tips

Lesson content:

- Initial Rigid Body Motion
- Overconstraint
- Contact with Quadratic Elements
- Unsymmetric Matrices in Finite-Sliding Problems
- Dynamic Instabilities
- Modeling Corners and Edges
- Contact and Convergence Guidelines
- Workshop 10: Snap Fit Analysis (IA)
- Workshop 10: Snap Fit Analysis (KW)
- Workshop 11: Analysis of a Radial Shaft Seal (IA)
- Workshop 11: Analysis of a Radial Shaft Seal (KW)





Appendix 1: Node-to-Surface Formulation

- Discretization
- Finite Sliding: Surface Considerations
- Small Sliding Characteristics
- Small Sliding: Local Contact Plane
- Small Sliding: Surface Considerations



Appendix 2: Contact Elements

- Surface-Based vs. Contact Element Approach
- Contact Elements
- Contact Element Output
- Contact Element Visualization

Appendix 3: Dynamic Contact using Implicit Integration

- Time Integration Issues
- Implicit Dynamics
- Damping
- Impact Problems



Appendix 4: Contact Logic and Diagnostics Tools

- Newton Method
- The Contact Algorithm
- Contact Diagnostics: Visual
- Contact Diagnostics: Text



Appendix 5: Additional Features

- Beam Contact
- Tie Constraints
- Rigid Bodies and Contact
- Analytical Rigid Surfaces
- Pre-Tensioning of Cross-Sections
- Pressure Penetration
- Contact in Linear Perturbation Procedures
- Initial Stresses for Contact



Appendix 6: Additional Contact Output

- Additional Field Output
- Master and Slave Surfaces
- Error Indicators
- Contact Area and Units
- Contact Opening
- Self Contact
- Nodal Contact Output Requests
- Whole Surface Output
- Whole Model Output



Appendix 7: Advanced Friction Models

- Anisotropic Friction
- Surface Slip Directions
- Nonlinear Friction Coefficients
- Kinetic Friction Model
- User Subroutine FRIC_COEF



Appendix 8: Contact Clearance

- Precise Specification of Clearances
- Initial Clearance with General Contact
- Initial Clearance with Contact Pairs

Appendix 9: Geometric Smoothing

- Geometric Smoothing for Curved Surfaces
- Applicability
- Examples
- General Contact
- Contact Pairs

Appendix 10: Resolving Overconstraints

- Four Bar Linkage Example
- Constraint Chains
- Removing Overconstraints